The Optimal Thresholding Technique for Image Segmentaion Using Fuzzy Otsu Method

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Article Info	ABSTRACT
Article history:	Image Segmentation plays a very important role in image processing. The single-mindedness of image segmentation is to partition the image into a set
Received May 22, 2015 Revised July 12, 2015 Accepted August 1, 2015	of disconnected regions with the homogeneous and uniform attributes like intensity, tone, color and texture. There are various methods for image segmentation but no method is suitable for low contrast images. In this paper, we are presenting an efficient and optimal thresholding image segmentation technique that can be used to separate the object and background pixels of
Keyword:	the image to improve the quality of low contrast images. This innovative method consists of two steps. Firstly fuzzy logics are used to find optimum
BCV Fuzzy Logic Otsu Segmentation	mean value using S-curve with automatic selection of controlled parameter to avoid the fuzziness in the image. Secondly, the fuzzy logic's optime threshold value used in Otsu method to improve the contrast of the image This method, gives better results than traditional Otsu and Fuzzy logic techniques. The graphs and tables of values show that the proposed method superior to traditional methods.
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1. INTRODUCTION

Image segmentation plays an important role in image processing and computer vision applications. It is often used to partition an image into separate regions, which ideally correspond to different real world objects. It is a major step towards content analysis and image understanding. Otsu method [1] is a very popular global automatic thresholoding technique, which can be applied to a wide range of applications. This method is selected by maximizing the discriminant measure n. Otsu method is nonparametric and unsupervised nature of threshold selection. In order to increases the effectiveness of calculation for the optimal thresholds of an image, Ping-Sung, et al [2], suggested a faster version of Otsu's method. In this method, first, a condition is defined that maximizing the modified between-class variance (BCV) that is same as to the condition of maximizing the usual BCV is proposed for image segmentation. Based on this condition, in order to find the optimal threshold value a recursive algorithm is designed. Based on improved thresholding algorithm, Ch. Hima Bindu [3], proposed a new optimized Otsu method. This method reduces the operating time and increases the reparability factor in medical image segmentation. D Liu, et al [4] proves that in multilevel thresholding based on minimizing the within-class variance, the objective function of both Otsu method and K-means method is same. In order to do multilevel thresholding, a two-stage Otsu optimization approach was proposed by D Hunang et al [5]. This method is called as modified two-stage multi threshold Otsu (TSMO). This procedure gives the same results as obtained by using traditional Otsu

method. The main advantage of this method is decreases the required computation time for large number of clusters.

X Yang et al, [6], presented a new technique that improves the performance of the Otsu algorithm. HJ Vala et al [7], provides the information about the different Otsu algorithms and compare the performances of these methods. VP Patel et al [8] implemented the Otsu method in different approaches like iteration approach and custom approach. They implemented these techniques in MATLAB and compare the results and shows that both has given almost the same threshold value for segmenting the image but custom approach requires less computations. Firstly, the idea of entropy for thresholding was used by Pun [10], this was extended by Kapur et al [9], in entropy based algorithms. This method concludes that when the summation of the background and object entries reaches its maximum, the threshold value is obtained. By using the pixels gray value and local average of neighborhood gray values of the pixels, a 2D histogram was determined and by using this Abutaleb extended Kapur's method using 2 D entropies [11]. As an enhancement, this technique is simplified by AD Brink [12].

In 1965, Zadeh proposed fuzzy logic in his research Fuzzy Sets [13].He well-defined the fuzzy sets and fuzzy logic in additional to the membership function which assign each grade to a value between 1 and 0 and introduces theoretical background. In segmentation process, Fuzzy based techniques were used by numerous authors. To select the threshold value, c-partition entropy fuzzy was used by Cheng et al [14]. To achieve this, maximum entropy principle and fuzzy c-partition was used. They have assumed a fixed and known number of the clusters and classified the pixels into these clusters. The ultra-fuzzy (fuzzy II) algorithms used to find the threshold value suggested by Tizhoosh [15]. C. Naga Raju et al [16], they derive fuzzy rules for π – function. By using effective selection of Region of Interest (ROI), this procedure is to optimize the image threshold. To estimate the fuzziness of an image and to determine an adequate threshold value, by utilizing the measure of fuzziness, Ambar Dutta, et al [17], proposed a two-stage fuzzy set theoretic approach to image thresholding. To avoid the fuzzy logic which produce optimal threshold value was proposed by C Naga Raju et al [18]. C Naga Raju et al [19], proposed a new technique to address the multidimensional optimized problem with optimal thresholding using fuzzy entropy for image enhancement.

2. PROPOSED METHOD

2.1. Otsu Method

Otsu method [1] is a very popular global automatic thresholoding technique. For the given image, the pixels can be denoted in *L* gray levels [0,1,2, ... L - 1]. At each gray level, the number of pixels denoted by n_i and the total pixels of image by $N = n_0 + n_1 + ... + n_{L-1}$. The gray level histogram is normalized by probability distribution function:

$$p_i = \frac{ni}{N}$$
, $p_i \ge 0$, $\sum_{i=0}^{L-1} p_i = 1$ (1)

We assigned k as the threshold value, to classify the background and object of the image, the normalized fraction of pixels will be used.

$$s_{x}(k) = \sum_{i=0}^{k} p(i)$$
⁽²⁾

$$s_v(k) = \sum_{i=K+1}^{L-1} p(i)$$
 (3)

$$s_x(k) + s_v(k) = 1$$
 (4)

The background mean and object mean of gray level value of pixels will be:

$$\mu_{\mathbf{x}}(\mathbf{k}) = \frac{\sum_{i=0}^{k} i p(i)}{p(i)} = \frac{1}{s_{\mathbf{x}}(\mathbf{k})} \sum_{i=0}^{k} i p(i)$$
(5)

$$\mu_{y}(k) = \frac{\sum_{i=k+1}^{L-1} ip(i)}{p(i)} = \frac{1}{s_{y}(k)} \sum_{i=k+1}^{L-1} ip(i)$$
(6)

The whole gray level image, whose mean value is calculated as:

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$$\mu = \frac{\sum_{i=0}^{L-1} ip(i)}{\sum_{i=0}^{L-1} p(i)} = \sum_{i=0}^{L-1} ip(i)$$
(7)

The background variance and object variance of gray level value of pixels will be:

$$\sigma_x^2(k) = \frac{\sum_{i=0}^k (i - \mu_x)^2 p(i)}{\sum_{i=0}^k p(i)} = \frac{1}{s_x(k)} \sum_{i=0}^k (i - \mu_x)^2 p(i)$$
(8)

$$\sigma_{y}^{2}(k) = \frac{\sum_{i=k+1}^{L-1} (i-\mu_{y})^{2} p(i)}{\sum_{i=k+1}^{L-1} p(i)} = \frac{1}{s_{y}(k)} \sum_{i=k+1}^{L-1} (i-\mu_{y})^{2} p(i)$$
(9)

Then, the whole gray level image, whose variance is calculated as:

$$\sigma^2 = \sum_{i=0}^{L-1} (i - \mu)^2 p(i) \tag{10}$$

Within-class and between-class variance The variance σ^2 can be defined as:

$$\sigma^{2} = s_{x}(k)\sigma_{x}^{2}(k) + s_{y}(k)\sigma_{y}^{2}(k) + s_{x}(k)(\mu_{x}(k) - \mu)^{2} + s_{y}(k)(\mu_{y}(k) - \mu)^{2}$$

= $\sigma_{w}^{2}(k) + \sigma_{b}^{2}(k)$ (11)

Where $\sigma_w^2(k)$ is the within – class variance and $\sigma_b^2(k)$ is the between-class variance.

2.1.1. Determining the threshold

Since the total variance σ^2 does not depend on k, the k minimizing σ_w^2 will be the k maximizing σ_b^2 . Let's consider maximizing σ_b^2 , we can rewrite σ_b^2 as:

$$\sigma_b^2 = \frac{[\mu(k) - \mu s_x(k)]^2}{s_x(k) s_y(k)}$$
(12)

Where, $\mu(k) = \sum_{i=0}^{k} i p(i)$.

In order to maximizes σ_b^2 , starts from the commencement of the histogram and check each gray level image value for the likelihood of being the threshold k.Otsu method proved that optimal threshold k^* is the value that maximize the between-class variance σ_b^2 as:

$$k^* = \arg\max\{\sigma_b^2(k)\}, 0 \le k \le L - 1 \tag{13}$$

2.1.2. Limitations of the Otsu method

We could not find a good union of thresholds to the global optimum for the gray level images by using the traditional Otsu algorithm. The Otsu algorithm is suitable only when there are two classes in the image. If there exists more than two classes in the image, the method must be customized in order to decide the multi thresholds. It allows the largest among-class variance and the least in-class variance. The image is divides into two groups by using Otsu algorithm, yet no actual sense is made by division because of no suitable mean value calculation with equation (15). In variable illumination conditions, this method could not be applied straight. To avoid this, Fuzzy S-curve membership function is used to calculate the optimum mean value.

2.2. Fuzzy Based Methodology

Abutaleb [11] and AD Brink [12] did some good work in obtaining the segmentation of a gray image incorporating the spatial correlation among the pixels of the image by constructing the 2D histogram. Fundamentally these methods attract maximum entropy criterion function to establish the optimal threshold for any given image.

Measures of fuzziness in contrast to fuzzy measures indicate the degree of fuzziness of fuzzy set. The membership degree of any value in the universe of discourse can be estimated by using any membership function. The membership degree can be expressed by a mathematical function $\mu_A(X_i)$ that allocates, to each element in the set, a membership degree between 0 to 1. Let be the universe of discourse and X_i is an element of A. Fuzzy set A in X is defined as $A = \{(X_i, \mu_A(X_i)), X_i \in X\}$.

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Figure 1. Typical Shape of S- Membership Function

S-membership function is used for modeling the membership degrees. This function is suitable to represent the set of bright pixels if image is considered as one dimensional signal and is defined as:

$$\mu_A(X) = S(X, a, b, c)$$

$$\mu_A(X) = \int_0^a 0 dx + 2 \int_a^b \left(\frac{x-a}{c-a}\right)^2 dx + \int_b^c \left(1 - 2\left(\frac{x-c}{c-a}\right)^2\right) dx + \int_c^{255} 1 dx$$
(14)

Where $b = \frac{1}{2}(a + b)$ initial seed sets, a and c controls S-function.

2.3. Automatic Selection of parameters

The S – function show in the Figure 1 can be controlled through *a* and *c* parameters. Parameter *b* is called the cross over point. Where the higher the gray level of a pixel, higher the membership value and vice versa. However the selection of parameters is difficult to automate the technique. Here the mean (μ) and standard deviation (σ) are calculated from equations (15) and (16), fuzzy seed set values a, b and c are estimated automatically as:

$$\mu = \frac{1}{N} \sum_{i=1}^{n} x_i p(i) \tag{15}$$

$$\sigma = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (x_i - \mu)^2} \tag{16}$$

From equations (15) and (16) fuzzy seed set values a, b and c are estimated automatically as:

$$b = \mu \tag{17}$$

$$a = \mu - \sigma \tag{18}$$

$$c = \mu + \sigma \tag{19}$$

by substituting these parameters in s-curve we can achieve better selection of parameters for low contrasted images.

3. QUALITY PARAMETERS

3.1. Mean

Mean is defined as the average gray levels of the image. In gray level image the mean is calculated as:

$$Mean(\mu) = \frac{1}{mn} \sum_{i=0}^{m-1} \sum_{j=0}^{n-1} g(x, y)$$
⁽²⁰⁾

Where g(x, y) is the gray level image, m and n are number of rows and number of columns of resulting image.

3.2. Standard Deviation

The standard deviation of gray level image is calculated as:

Std
$$(\sigma) = \sqrt{\frac{1}{mn} \sum_{i=0}^{m-1} \sum_{j=0}^{n-1} (g(x, y) - \mu)^2}$$
 (21)

Where g(x, y) is the gray level the image, m and n are the number of rows and number of columns of the resulting image and μ is the mean of the image.

4. RESULTS AND ANALYSIS

To elucidate the performance of the proposed methodology, we consider 17 images as an image set, it contains similar and dissimilar gray level histogram characteristics, changing from uni model to multi model histograms. For each sample image its histogram and a ground truth image, which is produced manually has been used as gold standard are shown in Figure 2, to compare results and their performance. We undertake this process with two measures similarity and diversity between the output image and its corresponding ground truth image. From the experiments for each test image we obtain mean (μ) computed from equation (20) is compared with gold standard images by all three different methods including Otsu, Fuzzy and Proposed is shown in Table 1. Figure 3 shows the comparison of means (μ) of three different methods. From the experiments for each test image we obtain standard deviation (σ) computed from equation (21) is compared with gold standard images by all three different methods including Otsu, Fuzzy and Proposed is shown in Table 2. Figure 4 shows the comparison of standard deviation (σ) of three different methods including Otsu, Fuzzy and Proposed is shown in Table 2. Figure 4 shows the comparison of standard deviation (σ) of three different methods including Otsu, Fuzzy and Proposed to the other two methods. The proposed method confirms the qualitative enhancement over the existing methods. Figure 2 shows threshold results obtained by various methods.

Image Name	Original	Otsu's	Fuzzy	Proposed	Image Name	Original	Otsu's	Fuzzy	Proposed
М 1	-		1	1	M 10			•	0
M 2	100	$\left(\cdot \right)$	10.7 ()		M 11				
мз		263 263 1			M 12				
M 4				<u> </u>	M 13	0		0	Ô
M 5					M 14	7-		Ţ	X
М 6	a hall	(1	la katti	La halli	M 15	211		\geq	
M 7					M 16				2011
M 8					M 17	C709		G709	¢709
м 9					IVI 17				

Figure 2. From Left to Right Original Images and Corresponding Results for the Three Algorithms Otsu, Fuzzy and Proposed Algorithms

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Imaga Nama		Mean (µ)	
inage Name -	Otsu's	Fuzzy	Proposed
M 1	0.0539	0.7366	0.4824
M 2	0.0188	0.3134	0.2124
M 3	0.0123	0.3927	0.2571
M 4	0.0084	0.5122	0.3549
M 5	0.0188	0.4250	0.3569
M 6	0.3057	0.7538	0.4443
M 7	0.0176	0.7344	0.4617
M 8	0.0548	0.3139	0.2654
M 9	0.0256	0.5559	0.3285
M 10	0.1618	0.6062	0.3420
M 11	0.0000	0.8936	0.5710
M 12	0.0127	0.2300	0.1507
M 13	0.0507	0.4966	0.2883
M 14	0.0060	0.2420	0.1634
M 15	0.0122	0.7832	0.4688
M 16	0.0299	0.8642	0.4981
M 17	0.0356	0.7151	0.4519

Table 1. Comparision of Mean (μ) for Different Methods

Table 2. Comparision of Standard Deviation (σ) for Different Methods

Image Name	S	Standard Deviation (σ)			
	Otsu's	Fuzzy	Proposed		
M 1	0.0767	0.2046	0.1148		
M 2	0.0303	0.1662	0.1014		
M 3	0.0257	0.1422	0.0815		
M 4	0.0086	0.0648	0.0646		
M 5	0.0117	0.0386	0.0374		
M 6	0.1344	0.1179	0.0673		
M 7	0.0450	0.0775	0.0477		
M 8	0.0361	0.0734	0.0449		
M 9	0.0722	0.0810	0.0409		
M 10	0.1348	0.2190	0.1112		
M 11	0.0086	0.1486	0.0746		
M 12	0.0162	0.1473	0.0863		
M 13	0.1153	0.1543	0.0881		
M 14	0.0186	0.1430	0.0733		
M 15	0.0550	0.1718	0.0940		
M 16	0.1148	0.1396	0.0696		
M 17	0.0953	0.1619	0.0875		



Figure 3. Comparison of Means for the Otsu, Fuzzy and Proposed Method



Figure 4. Comparison of Standard Deviation for the Otsu, Fuzzy and Proposed Method

5. CONCLUSION

In this paper by using three thresholding techniques of Otsu, Fuzzy and Proposed method, determined the optimal threshold values and they are tested with natural images as well as a variety of representing low contrasted images for image enhancement. The proposed method threshold value compared with existing Otsu and fuzzy thresholding techniques for image enhancement. It is proved that proposed method is best fit for even low contrasted images. By using mean and standard deviation, the tables and graphs are constructed. Even though the proposed method produces better results, it fails to show the important feature like moon in image M6 in Figure 2. The values of a and c of S-curve are defined automatically. We are not added any noise to the original image data set. In future work, we can overcome those problems by extending to speckle noise and poison noise removal and find all the important features of image.

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